Allocating heterogeneous goods through wait times and prices

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### Motivation: affordable housing

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- Applicants have **heterogeneous preferences** over location and quality
- More desirable units come with  ${\bf longer}$  wait times and  ${\bf higher}\ {\bf rents}$
- When choosing which project to apply for, applicants trade off:
  - 1. Preferences for different locations/apartments
  - 2. Wait times
  - 3. Rents
- While implementations differ, this  $\operatorname{core} \operatorname{trade-off}$  present across programs



- **Question:** How should we screen with wait times and prices when allocating heterogeneous goods?
- I study a stylized model with two goods and two screening instruments
- Main result: The designer should only use pricing to screen, even if she has no value for revenue

#### Literature

- Wasteful screening (Hartline and Roughgarden, 2008; Yang, 2021)
  - This paper: combines two wasteful screening instruments
- Wait times 'acting as prices' (Barzel, 1974; Leshno, 2022; Ashlagi et al., 2024)
  - This paper: shows wait times and prices screen on different things
- Mechanisms without money (Hylland and Zeckhauser, 1979; Budish, 2011)
  - This paper: money allowed but transfers are wasteful

# Model

#### Goods

- The designer distributes two kinds of goods,  $\boldsymbol{A}$  and  $\boldsymbol{B},$ 
  - There is  $\mu_A > 0$  of good A and  $\mu_B > 0$  of good B
- Agents' values for A and B given by two-dimensional types  $(a, b) \in [0, 1]^2$ 
  - Values a and b distributed independently on [0,1], according to G and H
  - G, H have densities g, h, full-support,  $\frac{G(v)}{g(v)}, \frac{H(v)}{h(v)}$  strictly increasing

#### Agents

- The designer chooses a menu of wait times and payments for each of the goods

- Each agent chooses which good she wants (if any) ...
- $\ldots$  and then chooses a payment and wait time option from this good's menu
- Type-(a, b) who gets a good, pays p and discounts it by x due to waiting gets utility:

 $\begin{array}{ll} x \cdot a - p & \text{if she gets } A, \\ x \cdot b - p & \text{if she gets } B. \end{array}$ 

- NB: waiting delays receipt  $\Rightarrow$  waiting cost multiplies value for the good!

#### Allocations

- The designer chooses **allocations** of:
  - 1. Payments  $p: [0,1]^2 \to \mathbb{R}_+$
  - 2. Discounting  $x : [0, 1]^2 \to [0, 1]$
  - 3. Goods:  $y: [0,1]^2 \to \{A, B, \emptyset\}$
- Subject to IC, IR and supply constraints:

for every  $(a,b), (a',b') \in [0,1]^2, \quad U[a,b,(p,x,y)(a,b)] \ge U[a,b,(p,x,y)(a',b')]$  (IC)

for every 
$$(a,b) \in [0,1]^2$$
,  $U[a,b,(p,x,y)(a,b)] \ge 0$  (IR)

$$\int \mathbb{1}_{\text{gets } A} \, \mathrm{d}F(a, b) \leq \mu_A, \qquad \int \mathbb{1}_{\text{gets } B} \, \mathrm{d}F(a, b) \leq \mu_B \tag{S}$$

### Designer

- She maximizes total agent welfare:

$$W = \int U[a,b, (p,x,y)(a,b)] \,\mathrm{d}F(a,b)$$

- NB: the designer puts no value on revenue!
  - E.g. social programs whose participants are poorer than the average taxpayer
  - Extreme assumption, but it works *against* the main result!

- Technical restriction: allowing only piecewise diff-able discounting allocations x(a, b)

# Feasible mechanisms

# Who gets which good?

- When neither good is free, some types do not participate  $(\emptyset)$
- The rest pick their favourite (payment, wait time) option for one of the goods
- Types on the **boundary** z indifferent between their best options for both goods
- Types below z pick some option for A, types above z pick some option for B



# Main result

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#### Theorem 1

The optimal mechanism allocates both goods without waiting. It posts a separate **price for each good**. The prices are chosen so that the whole **supply of both goods** is allocated.



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- I will give two complementary intuitions:
  - Intuition 1: explains why the result holds in a 1-dimensional case
  - Intuition 2: looks at what multidimensionality adds to the problem

# Intuition 1: 1D case

- Unit mass of agents with same b > 0 (sufficiently small) and  $a \sim G$  on [0, 1]
- Unlimited supply of good B, supply  $\mu_A$  of good A

#### Proposition 1

The optimal mechanism in the 1D model offers both goods without waiting. It offers good B for free and posts a price for good A.

#### 1D case

- Every feasible (deterministic) 1D mechanism allocates A to types above some  $\underline{a}$
- We can enforce this cutoff by asking recipients of A to **pay** or to **wait**
- We have  $U(a) = b + \int_a^a x(v) dv \dots$



- ... so payments leave more rents to inframarginal takers of A!

#### 1D case

- Wait time and payments mechanisms equally good for the cutoff type...
- ... but wait times more costly to inframarginal types...
- ... while payments 'equally costly' to everyone

- However, in 1D, the A-good always goes to an upper interval of types
- In 2D, combining wait times and payments can change sorting into goods!
- Intuition 2 explains why payments sort agents better

# Intuition 2: 2D case

Only wait times vs. only payments

### Only wait times

- Suppose  $\mu_A + \mu_B = 1$  and both goods are given for free
- Then everyone joins and wait-times 'clear the market'
- Type (a, b) chooses A if:

 $x_A \cdot a > x_B \cdot b$ 

- Ratio  $\frac{a}{b}$  determines choice of good



## Only payments

- Suppose  $\mu_A + \mu_B = 1$
- We can achieve the efficient allocation by pricing the overdemanded good!
- A-goods go to those with highest a b



## Using wait times vs. only payments

- With wait times, agents sort based on **relative values**
- Payments let us screen on agents' **absolute values**



- Absolute values are what matters, so payments sort agents better!

# Proof intuition

### Indirect utilities

- Agents in the A-region choose some (wait time, payment) options for good A...
- . . . and agents in the  $B\mbox{-}{\rm region}$  choose one for good B
- Their option choice **does not depend** on their value for the other good!
- Therefore, we can write indirect utilities cond. on getting goods A and B as:

 $U_A(a), U_B(b)$ 



#### Indirect utilities

- $U_A(a), U_B(b)$  are the indirect utilities cond. on joining goods A and B
- We thus have two 1D screening problems (one for each good)...
- ... connected by the boundary types' indifference conditions:

 $U_A(a_2) = U_B(z(a_2))$ 



- 1. Fix any boundary z and find the mechanism that optimally implements it
- 2. Find the optimal z among optimally implemented boundaries

## Optimally implementing a given boundary

- Fix a boundary  $\boldsymbol{z}$  and recall the following holds along it:

$$U_A(a) = U_B(z(a)) \quad \Rightarrow \quad x_A(a) = x_B(z(a)) \cdot z'(a)$$

- We have  $U_A(a) = \int_a^a x_A(v) dv$ , so we want  $x_A$  as large as possible
- Finding the best mechanism implementing  $z \Leftrightarrow$  finding the p.w. largest **non-decreasing**  $x_A, x_B : [0, 1] \rightarrow [0, 1]$  satisfying:

 $x_A(a) = x_B(z(a)) \cdot z'(a)$ 

## Picking the optimal boundary

- Fix some  $x_A(a_1)$  and suppose z is convex below it. Then:

$$z'(a) = \frac{x_A(a)}{x_B(z(a))} \quad \nearrow$$

- So  $x_A(a)$  must be strictly below  $x_A(a_1)$  for  $a < a_1 \dots$
- Best we can do is to push both  $x_A$  and  $x_B$  up until **monotonicity binds** for  $x_B$

$(a_1,b_1)$	
72(0)	

 $x_A(a_1)$ 

How flat can we make  $U_A$  and  $U_B$ ?

- Thus, in the optimal mechanism...
- on **convex** regions we have:

 $x_B(z(a)) = \text{const}, \quad x_A(a) \propto z'(a).$ 

- and on **concave** regions we have:

 $x_A(a) = \text{const}, \quad x_B(z(a)) \propto 1/z'(a).$ 



# Picking the optimal boundary

- These conditions tell us **how to optimally implement** each boundary z
- Now, look at any convex region of  $\boldsymbol{z}$
- Perturb z to find its **optimal shape** on it



Objective in terms of  $U_A$  and  $U_B$ , and z

- Recall the objective is:

$$\int U[a,b,(p,t,y)(a,b)] \,\mathrm{d}F(a,b).$$

- We can use the boundary structure to write it as:

$$\underbrace{\int_{\underline{a}}^{1} \int_{0}^{z(\min[a,\overline{a}])} f(a,v) dv \cdot U_{A}(a) \ da}_{\text{Get } A} + \underbrace{\int_{\underline{b}}^{1} \int_{0}^{z^{-1}(\min[b,\overline{b}])} f(v,b) dv \cdot U_{B}(b) \ db}_{\text{Get } B}$$

- We can similarly rewrite supply constraints in terms of  $\boldsymbol{z}$ 

### Objective in terms of $U_A$ and $U_B$ , and z

$$\int_{\underline{a}}^{1} \int_{0}^{z(\min[a,\overline{a}])} f(a,v) dv \cdot U_{A}(a) \ da \ + \ \int_{\underline{b}}^{1} \int_{0}^{z^{-1}(\min[b,\overline{b}])} f(v,b) dv \cdot U_{B}(b) \ db.$$

- Restricting to some region  $[\underline{v}, \overline{v}]$ , changing variables and integrating by parts gives:

$$U_A(\overline{v})G(\overline{v})H(z(\overline{v})) - U_A(\underline{v})G(\underline{v})H(z(\underline{v})) - \int_{\underline{v}}^{\overline{v}} \underbrace{x_A(a)}_{ ext{constant}} G(a)H(z(a))\,da.$$

- Objective depends only on z, so we can apply optimal control
- Turns out the optimal z has to be **linear on every such region**!

# Conclusions

#### Conclusions

- Many housing programs make participants trade off:

#### prefs. for goods vs. wait time vs. payments

- These screen differently! Wait times  $\rightarrow$  relative, payments  $\rightarrow$  absolute values
- My stylized model shows wait-times have **bad screening properties**

- While some wait time is often inevitable in reality...
- ... we should be worried about large **imbalances** in wait times!
- In those cases, we should **adjust prices**!

